



# Absolute Encoders

<b>Multiturn</b>	<b>Sendix absolute</b>	<b>7063 (Shaft) with ATEX approval</b>	<b>SSI</b>
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Explosion protection	
<b>EC type-examination certificate</b>	PTB09 ATEX 1106 X
<b>Category (gas)</b>	II 2G Ex d IIC T6
<b>Category (dust)</b>	II 2D Ex tD A21 IP6X T85°C
<b>Directive 94/9 EC</b>	EN 60079-0; DIN EN 60079-1 EN 61241-0; DIN EN 61241-1

Mechanical characteristics	
<b>Max. speed</b>	6 000 min <sup>-1</sup> continuous
<b>Starting torque</b>	< 0,05 Nm
<b>Weight moment of inertia</b>	4,0 x 10 <sup>-6</sup> kgm <sup>2</sup>
<b>Shaft load capacity</b>	radial 80 N axial 40 N
<b>Weight</b>	approx. 0,6 kg
<b>Protection acc. to EN 60 529</b>	IP 67
<b>Working temperature range</b>	-40°C ... +60°C
<b>Materials</b>	shaft stainless steel flange seawater-resistant Al, type AISiMgMn (EN AW-6082) (optional: stainless steel) housing seawater-resistant Al, type AISiMgMn (EN AW-6082) (optional: stainless steel) cable PVC
<b>Shock resistance acc. to DIN-IEC 68-2-27</b>	> 2500 m/s <sup>2</sup> , 6 ms
<b>Vibration resistance acc. to DIN-IEC 68-2-6</b>	> 100 m/s <sup>2</sup> , 55 ... 2000 Hz

General electrical characteristics	
<b>Supply voltage</b>	10 ... 30 V DC
<b>Current consumption (w/o output load)</b>	24 V DC max. 25 mA
<b>Reverse polarity protection for power supply (Ub)</b>	yes
<b>CE compliant acc. to</b>	EN 61000-6-2, EN 61000-6-4 and EN 61000-6-3
<b>RoHS compliant acc. to</b>	EU guideline 2002/95/EG

SSI interface	
<b>Output driver</b>	RS 485 Transceiver type
<b>Permissible load/channel</b>	max. 20 mA
<b>Signal level</b>	high typ 3,8 V low for I <sub>Last</sub> = 20 mA typ 1,3 V
<b>Short-circuit proof outputs</b>	yes <sup>1)</sup>
<b>Singleturn resolution</b>	10...14 bit and 17 bit <sup>2)</sup>
<b>Number of revolutions</b>	4096 (12 bit)
<b>Code</b>	Binär or Gray
<b>SSI clock rate</b>	< 14 bit: 50 kHz ... 2 MHz
<b>Monoflop time</b>	< 15 µs <sup>2)</sup>
Note: if clock starts cycling within monoflop time a second data transfer starts with the same data. If clock starts cycling after monoflop time, the data transfer starts with updated values. The update rate depends on clock speed, data length and monoflop time.	
<b>Time jitter</b>	up to 14 bit < 1 µ for 15 ... 17 bit < 4 µs
<b>Status and Parity bit</b>	upon request

1) Short-circuit with 0V or output, only one channel at a time, supply voltage correctly applied  
2) Other options upon request

SET input	
<b>Input</b>	high active
<b>Input type</b>	Comparator
<b>Signal level</b>	high min. 60 % of V <sub>+</sub> max: V <sub>+</sub> low max. 25 % of V <sub>+</sub> (V <sub>+</sub> = supply voltage)
<b>Input current</b>	< 0,5 mA
<b>Min. pulse duration (SET)</b>	10 ms
<b>Timeout after SET signal</b>	14 ms
<b>Response time (DIR input)</b>	1 ms
The encoder can be set to zero at any position by means of a High signal on the SET input. Other preset values can be factory-programmed. The SET input has a signal delay time of approximately 1 ms. Once the SET function has been triggered, the encoder requires an internal processing time of approximately 15 ms before the new position data can be read.	

DIR input	
A High signal switches the direction of rotation from the default CW to CCW. The reverse function can also be factory-programmed.	
If DIR is reversed when the device is already switched on, this will be interpreted as an error. The status output switches to Low.	

Status output	
<b>Output driver</b>	Open collector internal pull-up resistor 22 kohm
<b>Permissible load</b>	20 mA
<b>Signal level</b>	high +V low < 1 V
<b>Active at</b>	low
The status output serves to display various alarm or error messages. The status output is high (Open Collector with internal pull-up 22k) in normal operation.	

Power-on delay	
After Power-On, the device requires a time of approximately 150 ms before valid data can be read.	

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## Terminal assignment

for output circuit 1 or 2

Signal	GND	+V	+C	-C	+D	-D	SET	DIR	Stat	PE	PE
Cable marking	1	2	3	4	5	6	7	8	9	yellow/green	Shield

+V: Encoder power supply +V DC

GND: Encoder Ground GND (0V)

+C, -C: Clock signal

+D, -D: Data signal

SET: Set input. The current position becomes defined as position zero.

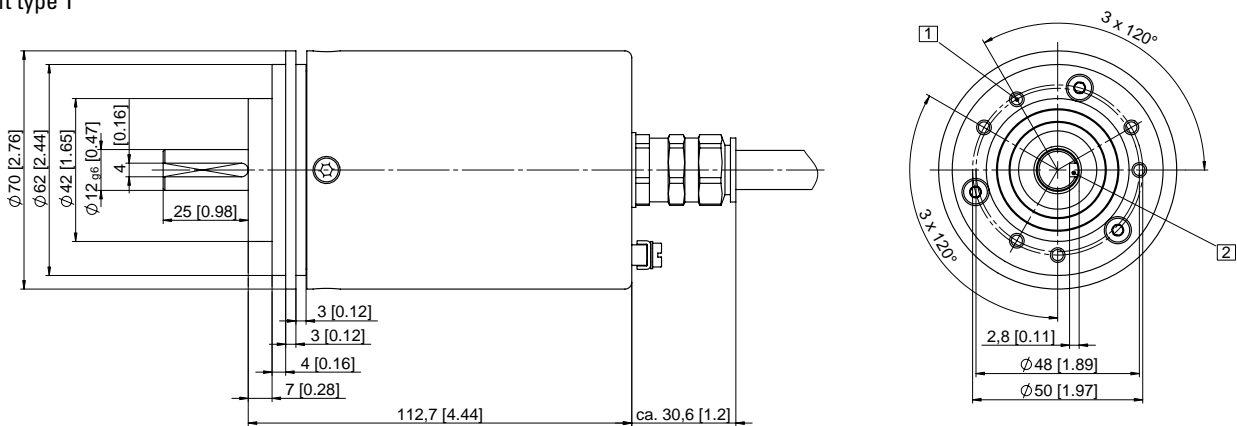
DIR: Direction input. If this input is active, output values are decreasing when shaft is turned clockwise

Stat: Status output

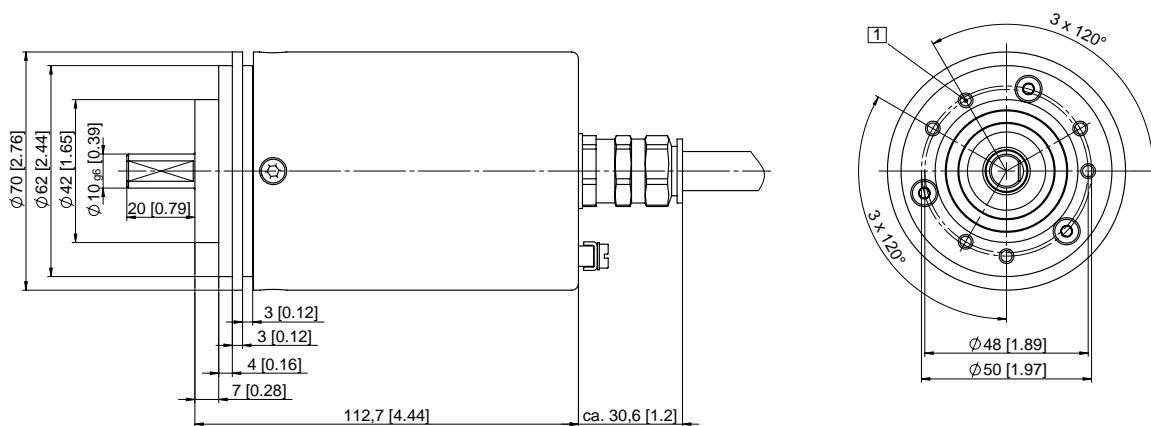
PE: Protective earth

## Dimensions

### Shaft type 1



### Shaft type 2



1 6 x M4, 10 [0,39] deep

2 Keyway for DIN6885-A-4x4x25 key